FINAL YEAR PROJECT REPORT

GSM GUIDED ROBOTIC ARM WITH OBJECT HANDLER

Submitted by

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ABSTRACT

The main theme of this project is to design a robotic arm which can move up and down and lift objects from one place to another. It is a car moving robot that can move in any direction.
The project is part of embedded system design. Embedded systems are such systems which are controlled by one or more processing cores which makes the use of PIC microcontroller which is programmed by embedded C instructions and use to interface other sensor modules.

Our project is entirely driven by wireless technology and is divided into two circuits.
1) Transmitter Circuit
2) Receiver Circuit

Mobile phones transmit certain frequencies when their buttons are pressed our project is operating on same principal, which in turn move our robot in different directions. Our specially designed robotic arm mounted on top of robot has wide range of applications.
Usually Radio Frequency (RF) circuits are used for wireless controlled robots which have limited frequency, limited range and limited control. To avoid these limitations and constraints, the use of mobile phone for the robot control is the best option. It provides the advantage of unlimited range of controlling the robot.

Key Notes: GSM, MICROCONTROLLER, MOTORS, MECHANICAL ARM